



A Transducer-Based Model for Representing Functional Constraints on Integer Sequences

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Key Ideas

- Describe mechanism to define many global constraints declaratively
- Seen as functional constraints on a sequence
 $c(R, [X_1, X_2, \dots, X_n])$
- Automatically generate constraints from description
- Based on automata with registers
- Provides basis for much more (not covered here):
 - Bounds
 - Redundant constraints
 - Interaction of constraints

Examples

- `nb_strictly_decreasing_sequence(2, [1, 1, 0, 0, 1, 0, 0, 1])`
- `max_width_group(2, [0, 1, 0, 1, 1])`
- `nb_stretch(6, [0, 1, 1, 1, 0, 1, 0, 1])`

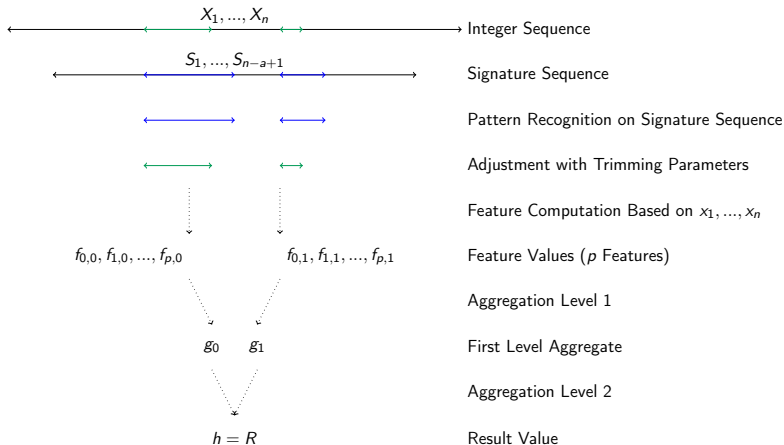
Why?

- Constraint solvers depend on global constraints for performance
- But each constraint is an algorithm on its own
- Too many to implement
- Impossible to be confident in correctness
- Too many to remember
- We need a more systematic way to describe and implement global constraints

Note

- We describe the process based on integer sequences
- The derived mechanism also works as a constraint on finite domain variables

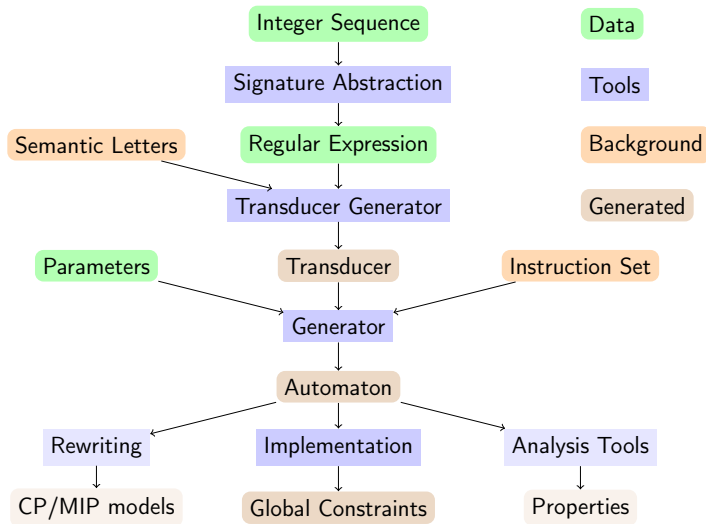
Computing with Integer Sequences



Signature Definition

- Time-Series: binary $<, =, >$
- Unary example: \in, \notin for value set V , `max_width_group`
- Other binary example: $=, \neq$, `nb_stretch`
- k-ary: Compute signature value from sub-sequences of length k
- Unary classification
- Extended binary $\ll, <, =, >, \gg$

The Scheme

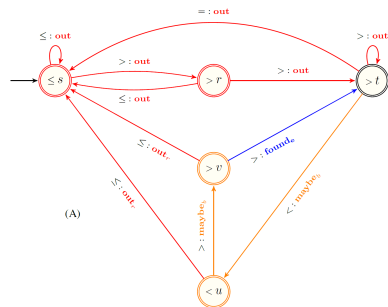


But you did all this already for time-series?

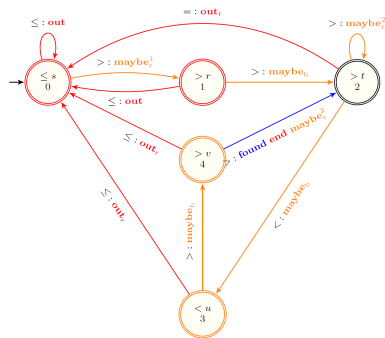
- This is a second-generation study
- Time-series were a special case
 - Specific, binary signature (<,=,>)
 - Initially hand-crafted transducers
 - Feature/Aggregator set limited
 - Only one feature considered per constraint
- Some issues were not dealt with elegantly
 - Mix-up of pattern recognized and feature value computed
 - Some pattern were not expressible

Compare: Old vs New

bump_on_decreasing_sequence, Reg. expr ' $>><>>$ ', Signature ' $<=>$ '



Old



New

Example Recognition ' >><>> '

> > > < > >

out out out m_b m_b f_e

Old (Only for $b=2$)

m_r^1 m_b m_r^2 m_b m_b f, e, m_r^2

New

The Generated Automaton

- Based on the generated transducer
- Five registers
 - Level 4: aggregated value h
 - Level 3: aggregated value g
 - Level 2: feature value of current confirmed, but uncompleted pattern
 - Level 1: potential feature value of unconfirmed pattern
 - Level 0: potential feature value of unconfirmed pattern

The Micro-Instructions

micro instruction register updates

compute(ℓ, b, v) : **if** $b = 0$ **then** $V_\ell \leftarrow \phi_\ell(V_\ell, v)$ **else** $V_\ell \leftarrow \phi_\ell(V_\ell, -v)$
reset(ℓ) : **for** $k \in [0, \ell]$ **do** $V_k \leftarrow \text{id}_k$
transmit(c, b, ℓ) : **if** $c = 1$ **then** $V_{\ell+1} \leftarrow V_\ell$
 else if $b = 1$ **then** $V_{\ell+1} \leftarrow \phi_{\ell+1}(V_{\ell+1}, |V_\ell|)$
 else $V_{\ell+1} \leftarrow \phi_{\ell+1}(V_{\ell+1}, V_\ell)$
set(ℓ, k) : **if** $\text{before} + 1 - k > 0$ **then** $V_\ell \leftarrow \text{id}_\ell$
 else if $\text{before} + 1 - k = 0$ **then** $V_\ell \leftarrow \delta_f^i$
 else $V_\ell \leftarrow \phi_\ell(\delta_f^{i-k+1+\text{before}}, \dots, \delta_f^i)$

The Macro-Instructions

letter	precondition	macro instruction code
maybe_b	$\left(s \notin skip \wedge d > before \right)$	compute $(1, 0, \delta_f^i)$, transmit (0, 0, 0), reset (0)
	$\left(s \in skip \wedge d > before \right)$	compute $(0, 0, \delta_f^i)$
maybe_r^k		reset (1), set (1, k)
out_r		reset (1)
found		compute (1, <i>balance</i> , κ), transmit (1, 0, 1), reset (1)
maybe_a		compute $\left(1, balance, \delta_f^{i+a-1-after} \right)$
in		compute $\left(1, balance, \delta_f^{i+a-1-after} \right)$, transmit (0, 0, 1), reset (1)
end		transmit (0, <i>balance</i> , 2), transmit (0, 0, 3), reset (2)

Limitations

- Complexity of scheme
 - Initial learning curve
 - Amortized over many constraints
- No guarantees about consistency levels achieved
 - More reasoning possible (similar to time-series results)
 - Better correct and slow than fast and wrong